Bin Picking solutions overview

	Localization SDK	Locator	Bin Picking Studio	Bin Picking Application
Vision system - *Where are the parts?*	✔	✔	✔	✔
Decision logic - *Which part to pick?*	-	Simple	✔	✔
Communication - *How to tell the robot?*	-	Simple	✔	✔
Path planning avoiding collision - *How to get there and back?*	-	-	✔	✔
Installation & service & support	-	-	Support only	✔

Bin Picking solutions

	3D Localization C++ SDK	Locator	Bin Picking Studio	Bin Picking Application
Object recognition by CAD model	✔	✔	✔	✔
Robot-camera calibration SW	On demand	✔	✔	✔
Communication interface with robot	-	Simple	Full	Full
Vision controller	-	✔	✔	✔
Path planning & collision avoidance	-	-	✔	✔
Vision system feasibility study	-	-	On demand	✔
Gripper design support	-	-	On demand	✔
Installation & Commissioning	-	-	On demand - Central Europe	✔
Training	-	-	On demand	✔
Configuration / Usage	On user PC	Directly on vision controller	Vision controller or Cloud via *web application*	Preconfigured
Delivery	Worldwide	Worldwide	Worldwide	Central Europe